



FIR Fractional Hilbert Transformers With Raised-Cosine Magnitude Response

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Outline

- Introduction
- Fractional Hilbert transformer with raised-cosine magnitude response
- Design of FIR
 - fractional Hilbert transformers
 - conventional Hilbert transformers
 - complex Hilbert filters
- Examples
- Conclusions



Introduction

- Fractional Hilbert transformers are **phase shifters**
 - 90-degrees phase shifters are called conventional transformers
- The design of **fractional transformers** often includes the design of **conventional transformers**
- Some designs of fractional transformers can be used to obtain **complex Hilbert filters**
- Nowadays, they are usually realized as digital systems



Introduction

- Transfer function of transformers
 - **FIR**
 - IIR
- Common design methods
 - FIR conventional transformers
 - minimax, least-squares, weighted least-squares, maximally flat and flat approximations
 - FIR fractional transformers
 - from previously designed conventional transformer
 - **directly design**
 - window method
 - maximally flat approximation



Introduction

- We found **the Fourier series method** useful for the design of fractional transformers
 - originates from early phase of FIR filter design
 - results in **the least-squares approximation**
 - the impulse response is truncated by the Fourier window
 - ⇒ **oscillatory behavior of the obtained magnitude (the Gibbs phenomenon)**
- Decreasing the Gibbs phenomenon
 - window with smooth decay
 - **smoothing the transition band**



Introduction

- We propose FIR fractional Hilbert transformers with raised-cosine magnitude response
 - good energy concentration of the impulse response
 - good control of the band of interest
 - closed-form method
 - fast and robust design

Fractional Hilbert Transformer With Raised-Cosine Magnitude Response

Frequency Response

- The **ideal** fractional Hilbert transformer is an ideal phase shifter
- The ideal frequency response

$$H_i(\omega) = \begin{cases} e^{j\varphi} & , -\pi < \omega < 0 \\ e^{-j\varphi} & , 0 < \omega < \pi \end{cases}$$

unity magnitude

constant phase

φ is fractional phase shift

⇒ The ideal response is approximated within some **band of interest**

- We want to design a transformer using the **Fourier series method**

⇒ The impulse response should be well localized

⇒ Smooth transition bands are required

- We use **bandpass raised-cosine magnitude response**

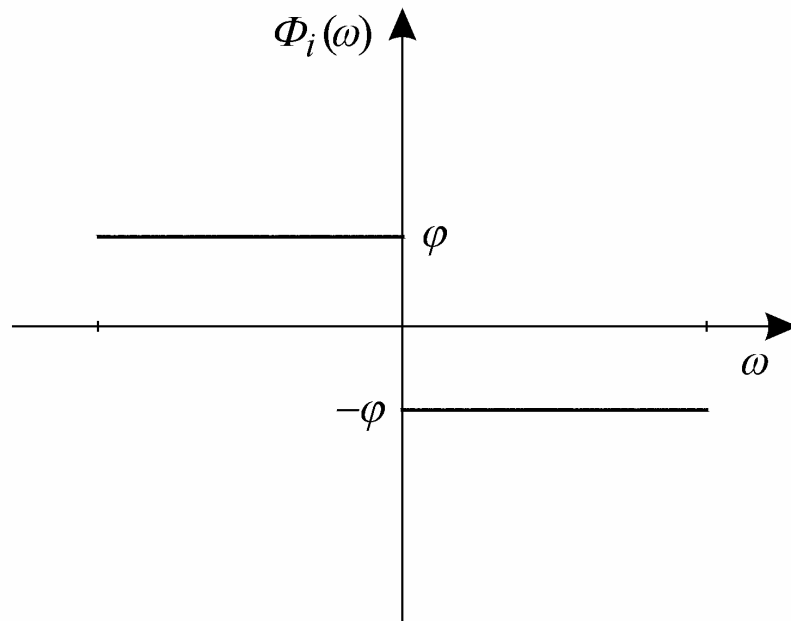
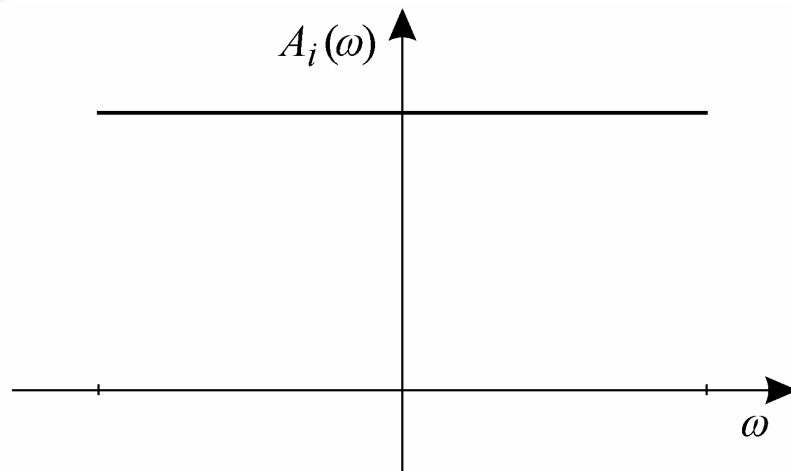
$$A_{BP}(\omega) = \begin{cases} \frac{1}{2} - \frac{1}{2} \cos\left(\pi \frac{|\omega| - \omega_1}{\omega_2 - \omega_1}\right), & \omega_1 < |\omega| < \omega_2 & \text{transition band} \\ 1, & \omega_2 \leq |\omega| \leq \omega_3 & \text{band of interest} \\ \frac{1}{2} + \frac{1}{2} \cos\left(\pi \frac{|\omega| - \omega_3}{\omega_4 - \omega_3}\right), & \omega_3 < |\omega| < \omega_4 & \text{transition band} \\ 0, & \text{otherwise} & \end{cases}$$

- The **desired** frequency response

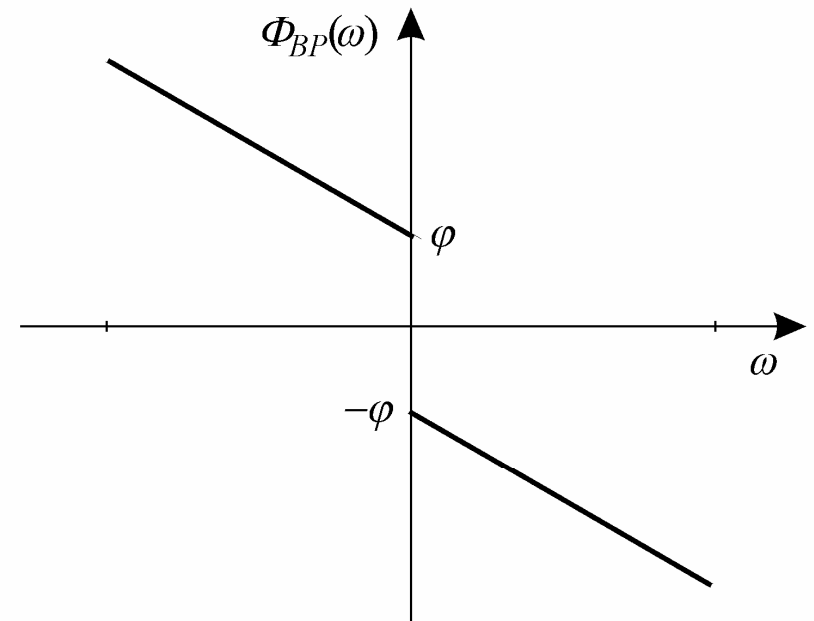
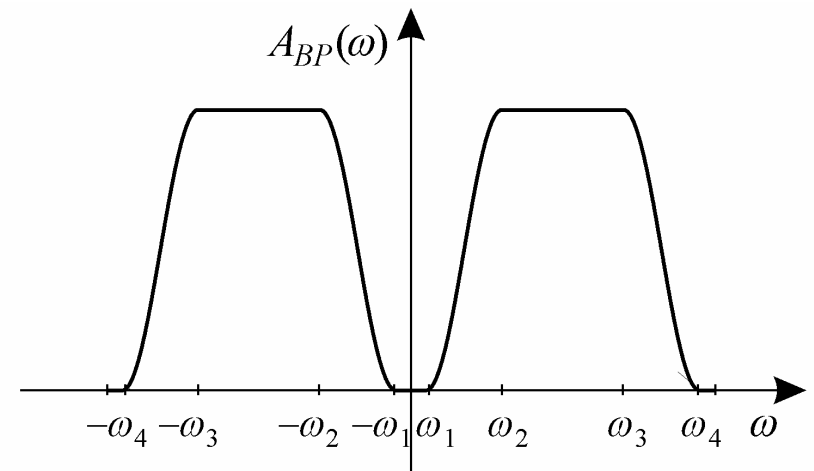
$$H_{BP}(\omega) = \begin{cases} A_{BP}(\omega)e^{j(\varphi - D\omega)} & , -\pi \leq \omega < 0 \\ A_{BP}(\omega)e^{-j(\varphi + D\omega)} & , 0 \leq \omega < \pi \end{cases}$$

D is delay

Ideal frequency response



Desired frequency response



Impulse Response

- The linear combination of two **lowpass responses**

$$H_{BP}(\omega) = H_{LP2}(\omega) - H_{LP1}(\omega)$$

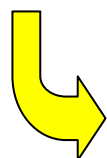


$$\omega_3 < |\omega| < \omega_4$$



$$\omega_1 < |\omega| < \omega_2$$

$$H_{LP}(\omega) = \begin{cases} A_{LP}(\omega)e^{j(\varphi-D\omega)} & , -\pi \leq \omega < 0 \\ A_{LP}(\omega)e^{-j(\varphi+D\omega)} & , 0 \leq \omega < \pi \end{cases}$$

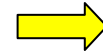


$$A_{LP}(\omega) = \begin{cases} 1 & , 0 \leq |\omega| \leq \omega_p \\ \frac{1}{2} + \frac{1}{2} \cos\left(\pi \frac{|\omega| - \omega_p}{\omega_s - \omega_p}\right) & , \omega_p < |\omega| < \omega_s \\ 0 & , \text{otherwise} \end{cases}$$

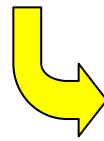
- The **lowpass** impulse response

$$h_{LP}(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_{LP}(\omega) e^{j\omega n} d\omega$$

$$h_{LP}(n) = \begin{cases} \underline{s(n)a(n) + b(n)}, & n \neq D \\ \frac{\omega_p + \omega_s}{2\pi} \cos \varphi, & n = D \end{cases}$$



$$s(n) = \frac{\sin \left[\frac{\omega_p + \omega_s}{2} (n - D) - \varphi \right]}{\pi(n - D)}$$



$$a(n) = \begin{cases} \frac{\cos \left[\frac{\omega_s - \omega_p}{2} (n - D) \right]}{1 - \left[\frac{\omega_s - \omega_p}{\pi} (n - D) \right]^2}, & n \neq D \pm \frac{\pi}{\omega_s - \omega_p} \\ \frac{\pi}{4}, & n = D \pm \frac{\pi}{\omega_s - \omega_p} \end{cases}$$



$$b(n) = \frac{\sin \varphi}{\pi(n - D)}$$

- The **bandpass** impulse response

$$h_{BP}(n) = h_{LP2}(n) - h_{LP1}(n)$$

$$h_{BP}(n) = \begin{cases} \underline{s_2(n)a_2(n) - s_1(n)a_1(n)}, & n \neq D \\ \frac{\omega_3 + \omega_4 - \omega_1 - \omega_2}{2\pi} \cos \varphi, & n = D \end{cases}$$



Design of Fractional Transformers

- The transfer function of an FIR fractional Hilbert transformer of the N th order

$$H_{FHT}(z) = \sum_{n=0}^N h_{FHT}(n)z^{-n}$$

- Fourier series method

$$h_{FHT}(n) = h_{BP}(n) \quad ; \quad n = 0, 1, \dots, N$$

\Rightarrow Additional window is not required!

- The **best LS approximation** is obtained for delay

$$D = \frac{N}{2}$$

Design of Fractional Transformers

Example 1

■ $N=60$

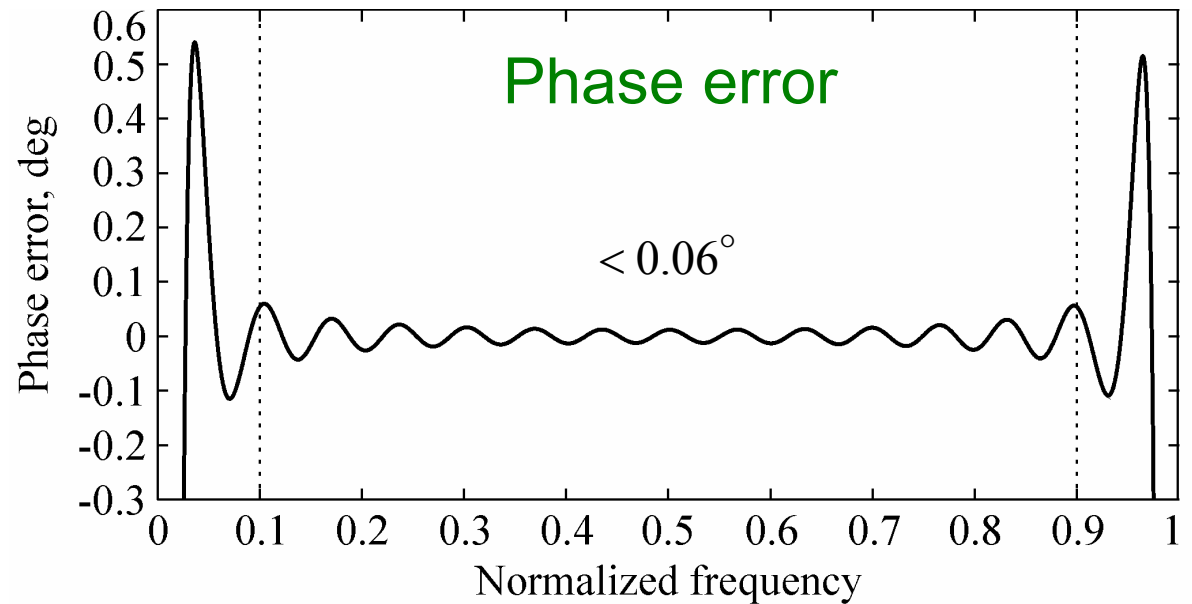
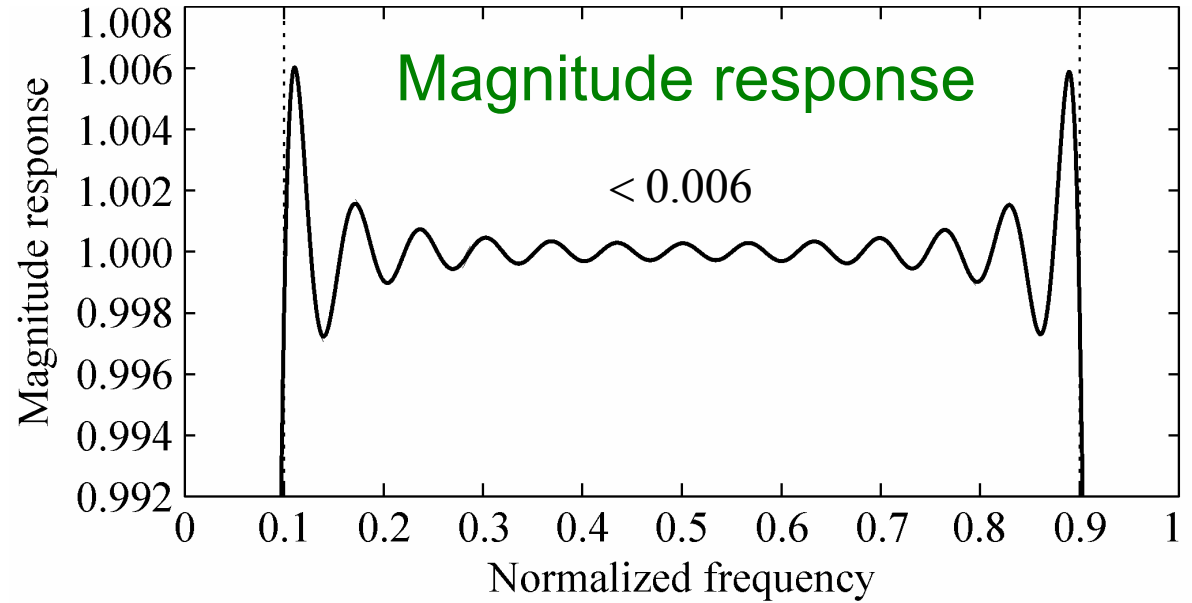
■ $\varphi=\pi/4$

■ $\omega_1=0$

$\omega_2=0.1\pi$

$\omega_3=0.9\pi$

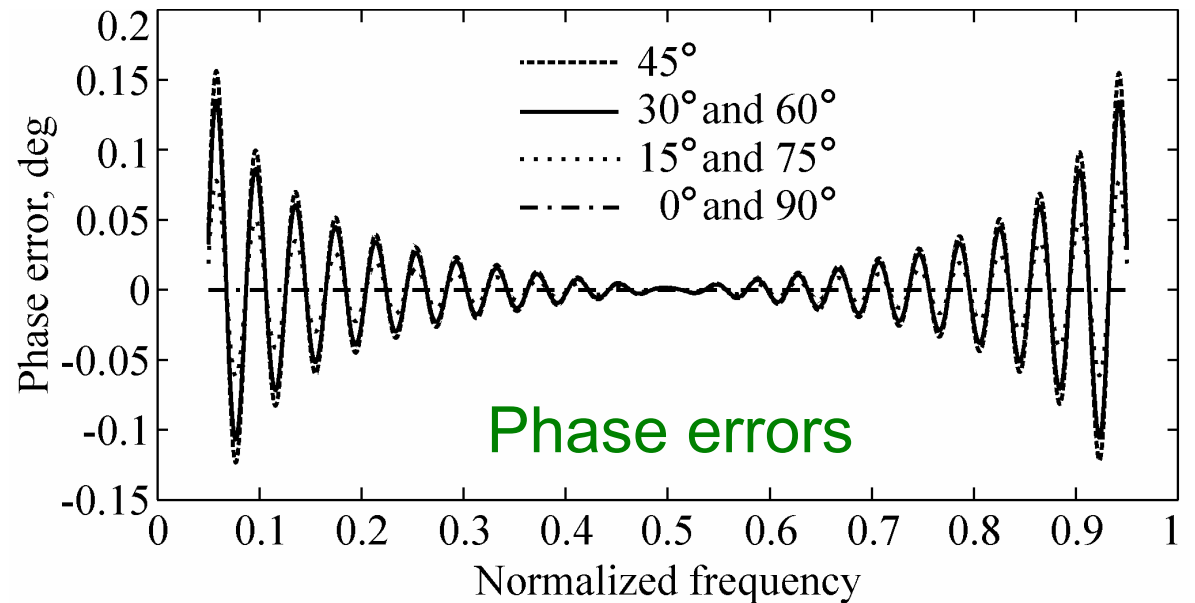
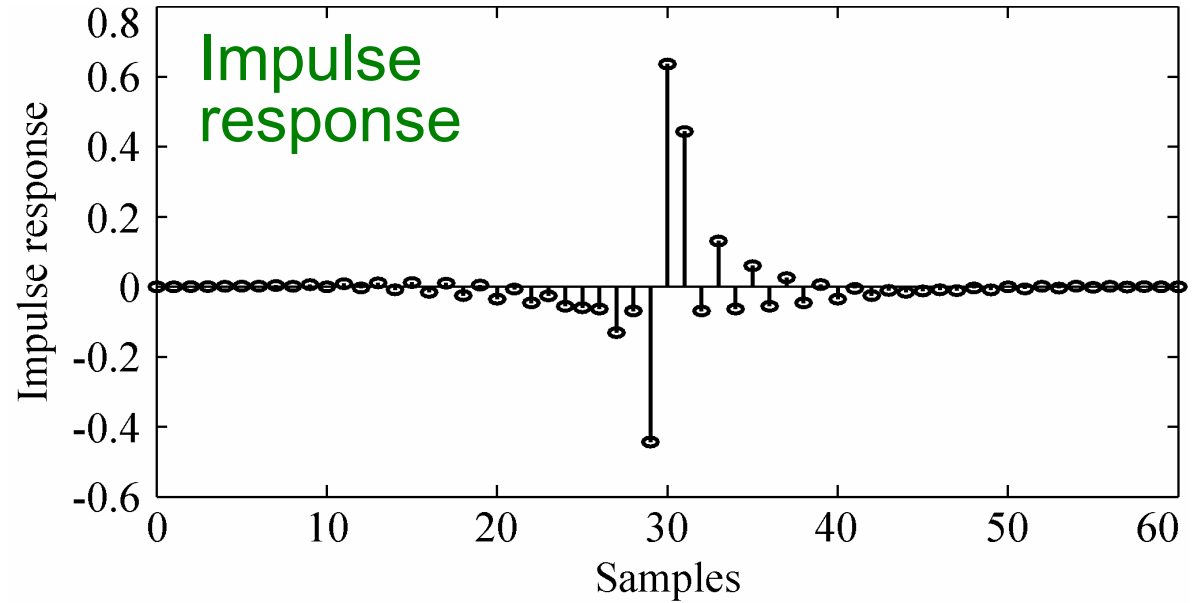
$\omega_4=\pi$



Design of Fractional Transformers

Example 2

- $N=100$
- various φ
- $\omega_1=0$
- $\omega_2=0.05\pi$
- $\omega_3=0.95\pi$
- $\omega_4=\pi$



Design of Fractional Transformers

- The **quality of approximation** is determined by the energy of the neglected impulse-response tails

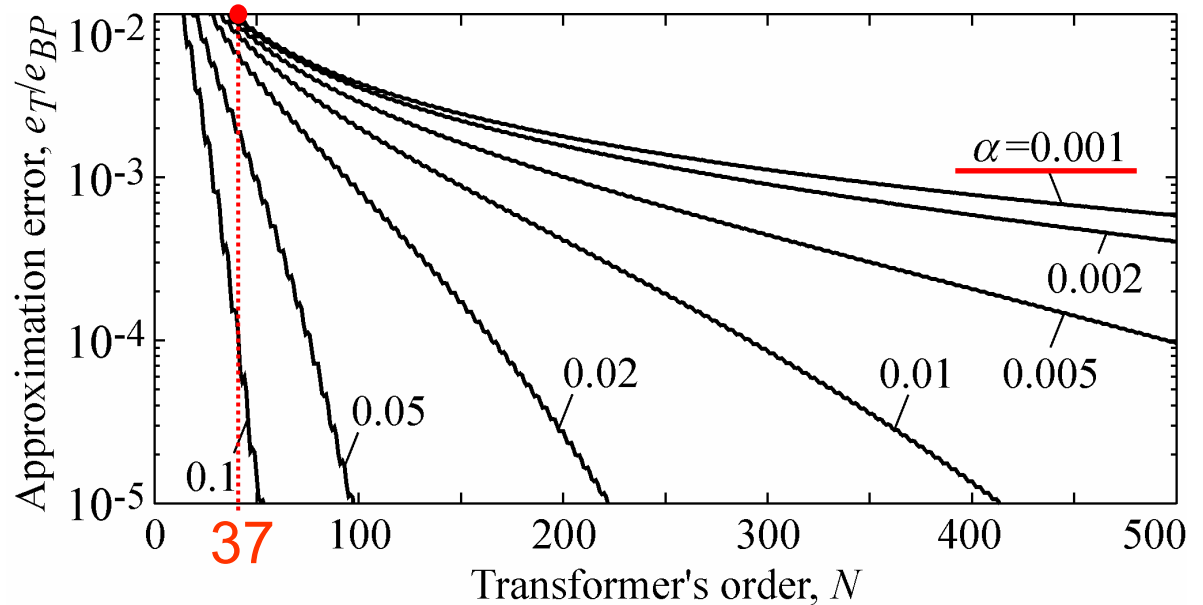
$$e_T = e_{BP} - e_{FHT}$$

$$e_{BP} = \frac{3(\omega_4 - \omega_1) + 5(\omega_3 - \omega_2)}{8\pi} \quad \leftarrow \quad \leftarrow e_{FHT} = \sum_{n=0}^N [h_{FHT}(n)]^2$$

- The relative approximation error = $\frac{e_T}{e_{BP}}$

Example 3

- $\varphi = \pi/4$
- $\omega_1 = 0$
- $\omega_2 = \alpha\pi$
- $\omega_3 = (1-\alpha)\pi$
- $\omega_4 = \pi$



Design of Conventional Transformers

- Special case in the design of fractional transformers
 - $\varphi = \pi/2$
- Special case in the design of conventional transformers
 - N is odd
 - $\omega_3 = \omega_4 = \pi$

\Rightarrow Highpass transformer

- Impulse response of highpass transformer

$$h_{BP}(n) = s_2(n)a_2(n) - s_1(n)a_1(n) \quad , \quad n \neq D$$



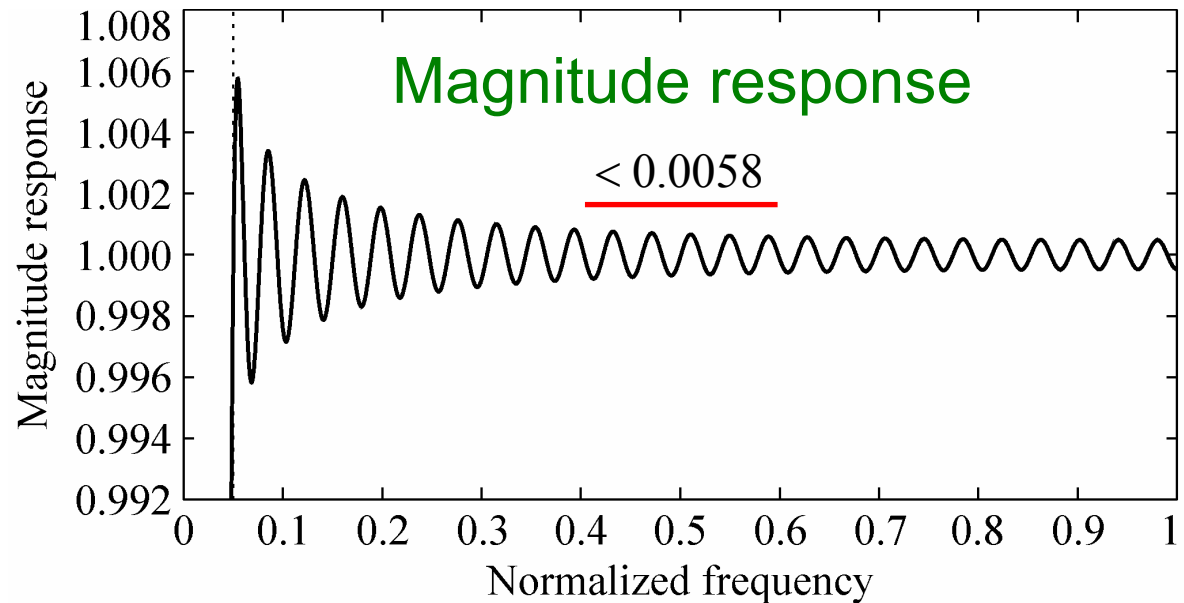
$$= 0$$

\Rightarrow $h_{HP}(n) = -s_1(n)a_1(n)$

Design of Conventional Transformers

Example 4

- $N=101$
- $\omega_1=0$
 $\omega_2=0.05\pi$



- The bandpass transformer with $N=100$,
 $\omega_3=0.95\pi$ and $\omega_4=\pi$ has the ripple < 0.0065

Design of Complex Hilbert Filters

- The presented transformers can be used in the design of systems with **complex coefficients**

⇒ **Hilbert filters**

- Hilbert filters are bandpass filters that pass only positive frequencies
- We propose the **raised-cosine magnitude over the positive frequencies**
- Impulse response

$$h_{PP}(n) = \frac{1}{2} h_{BP}(n) + j \frac{1}{2} \hat{h}_{BP}(n)$$

↓
 $\varphi = \beta$

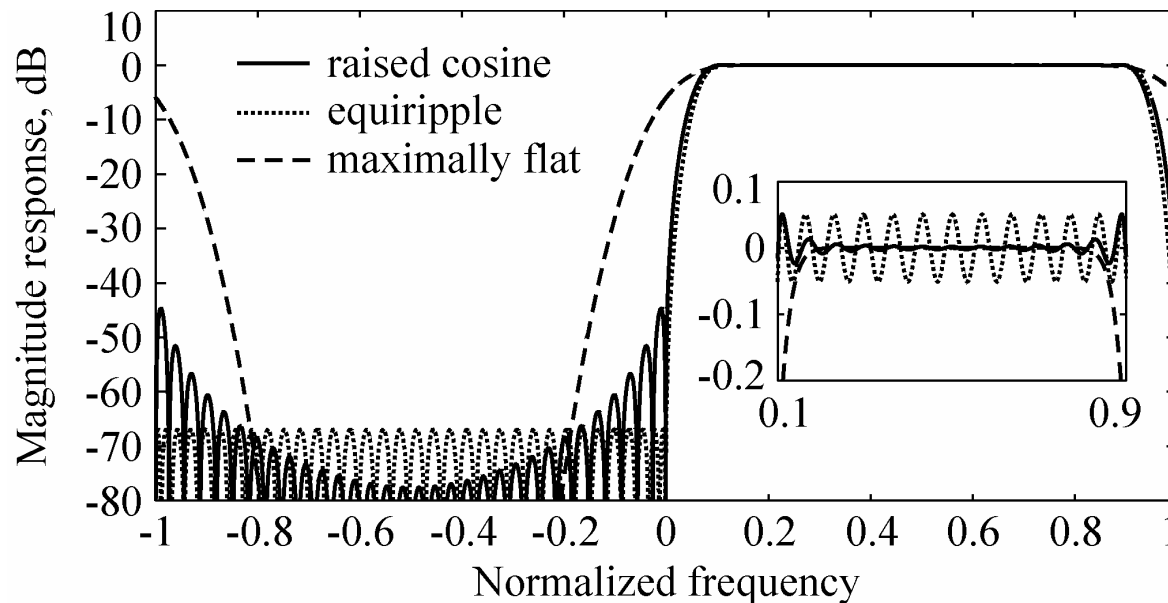
↓
 $\varphi = \beta + \pi/2$

β is an arbitrary phase shift

Design of Complex Hilbert Filters

Example 5

- Raised-cosine filter with $N=61$, $\beta=\pi/4$, $\omega_1=0$, $\omega_2=0.1\pi$, $\omega_3=0.9\pi$, $\omega_4=\pi$
- Comparison with
 - equiripple filter with the **same passband ripple**
 - maximally-flat filter with **flatness at $\omega=\pi/2$**





Conclusions

- The Fourier series method might still be attractive because it is **simple and straightforward**
- We used it to develop a **class of fractional Hilbert transformers**
- The transformers approximate **raised-cosine magnitude** with fractional phase shift in the **least-squares sense**
- The used impulse response
 - is well localized in time
 - enables the design of efficient Hilbert transformers and filters **without the need for additional window**