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# Design of CIC Compensators With SPT Coefficients Based on Interval Analysis

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# Outline

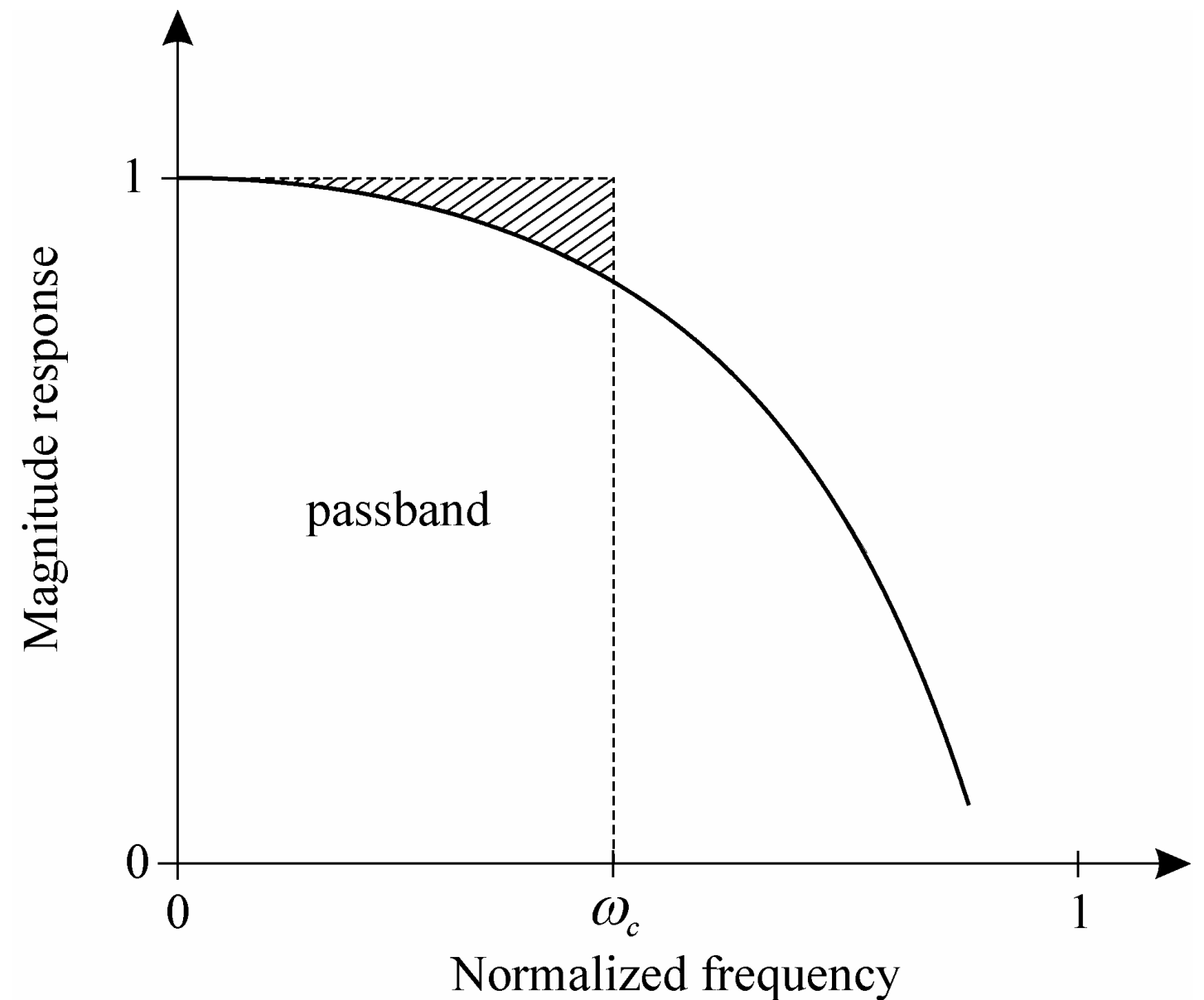
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- Introduction
- CIC compensator with SPT coefficients based on minimax error criterion
- Features of proposed CIC compensators
- Conclusion

# Introduction

- Digital down converters usually employ Cascaded-Integrator-Comb (CIC) filter in the first stage
- CIC filter
  - multiplierless structure
  - significant **passband droop**



# Reduction of Passband Droop

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- Modifying the original CIC structure
  - sharpening technique
    - Kwentus *et.al.* 1997, Stephen *et.al.* 2004, Dolecek *et.al.* 2005
- Connecting an additional filter in the cascade with the CIC decimator
  - **CIC compensator**
    - Yeung *et.al.* 2004, Kim *et.al.* 2006, Dolecek *et.al.* 2008, Dolecek 2009, Dolecek *et.al.* 2010, Molnar *et.al.* 2011, Vazquez *et.al.* 2012.

# CIC Compensator

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- FIR filter with linear phase
- Multiplierless structure is preferable
  - Coefficients are expressed as the sum of powers of two (SPT)
- Various multiplierless compensators have been proposed
  - Compensator with three and five coefficients
  - Compensation over wide and narrow band
- Various criteria have been used
  - Least squares, minimax, maximally flat

# In this paper...

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- CIC compensator with SPT coefficients
- Minimax error criterion
- Optimization based on the interval analysis
  - Results in global solution!
- Recently, it has been used in the design of low-order FIR filters with SPT coefficients
- Here, we modify it for the design of CIC compensator

# Ideal vs. FIR Compensator

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- The amplitude response of the CIC filter of order  $N$  and decimation factor  $R$

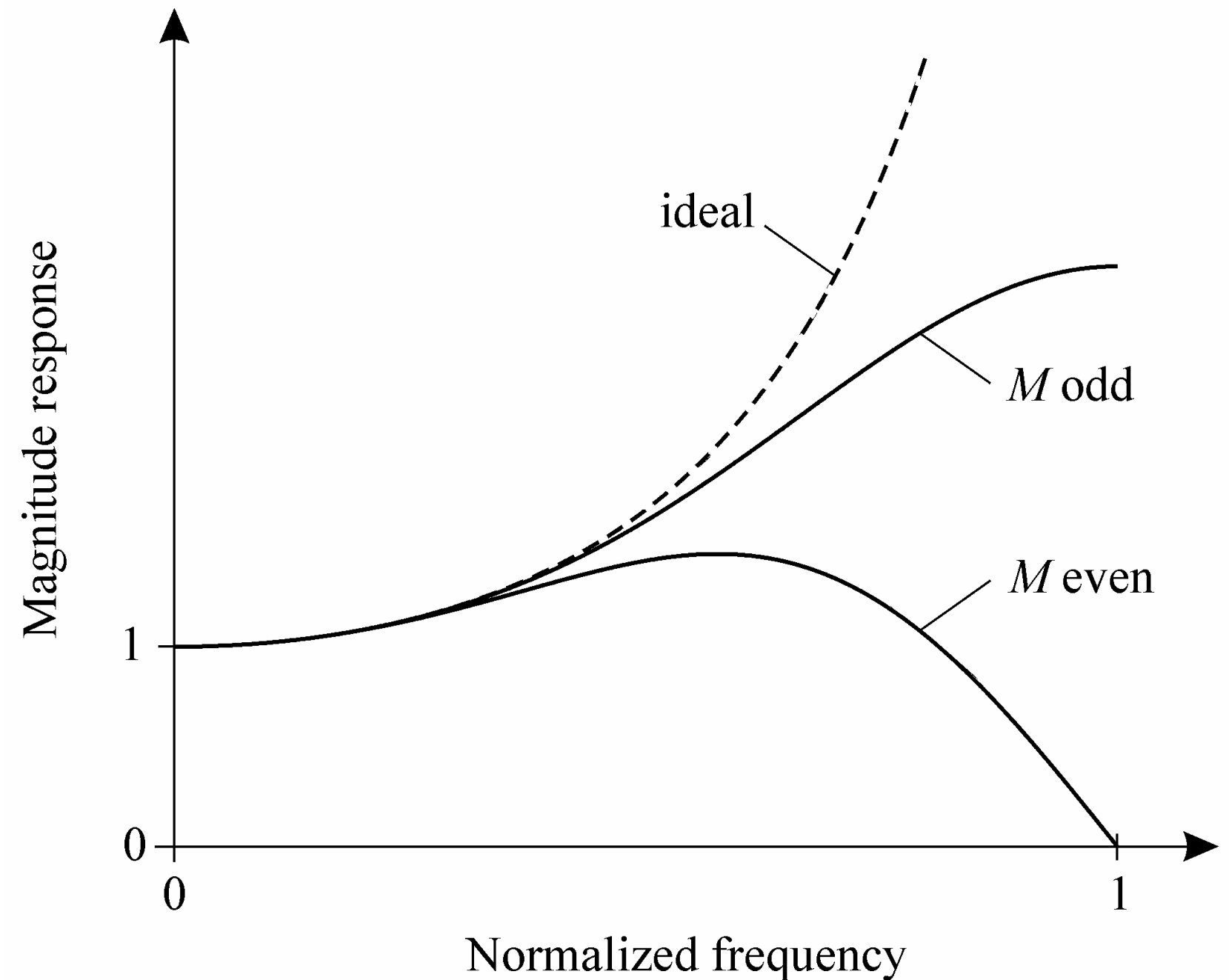
$$H_{CIC}(\omega) = \left[ \frac{1}{R} \frac{\sin\left(\frac{\omega R}{2}\right)}{\sin\left(\frac{\omega}{2}\right)} \right]^N$$

- The amplitude response of the **ideal compensator** is

$$H_C(\omega) = \frac{1}{H_{CIC}\left(\frac{\omega}{R}\right)}$$

# Ideal vs. FIR Compensator

- **FIR compensator** with  $M$  coefficients
- Compensator with odd number of coefficients is considered





# Minimax Approximation with SPT Coefficients

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- Objective is to find the optimum SPT coefficients of the compensator which results in the minimax approximation
- Such a design is described by

$$\mathbf{a}_{opt} = \arg \min_{\mathbf{a}} [\varepsilon(\mathbf{a})]$$

subject to :  $\mathbf{a}$  is SPT representable

- The **objective function** has the form

$$\varepsilon(\mathbf{a}) = \max_{|\omega| \leq \omega_c} \left| 1 - H_{CIC} \left( \frac{\omega}{R} \right) H(\omega, \mathbf{a}) \right|$$

# Minimax Approximation with SPT Coefficients

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- The problem is solved by using the optimization based on **interval analysis**

- In the paper

M. Vucic, G. Molnar, and T. Zgaljic, “Design of FIR filters based on interval analysis,” in Proc. MIPRO, vol. MEET, 2010.

the authors deal with the objective function

$$y(\mathbf{x}) = \max_{\omega \in \Omega} \left[ W(\omega) | H_a(\omega, \mathbf{x}) - H_d(\omega) | \right]$$

- Here, the interval extension of  $\varepsilon(\mathbf{a})$  can be easily obtained by using the extensions of elementary operations

# Minimax Approximation with SPT Coefficients

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- Vector  $\mathbf{a}$  contains only right-hand side samples

$$a(m) = h\left(m + \frac{M-1}{2}\right) \quad ; \quad m = 0, 1, \dots, \frac{M-1}{2}$$

- Amplitude response of compensator

$$H(\omega, \mathbf{a}) = a(0) + 2 \sum_{m=1}^{(M-1)/2} a(m) \cos(m\omega)$$

- SPT coefficient with a given wordlength  $K$

$$a(m) = \sum_{k=1}^K b(m, k) 2^{-k} \quad b(m, k) \in \{-1, 0, 1\}$$

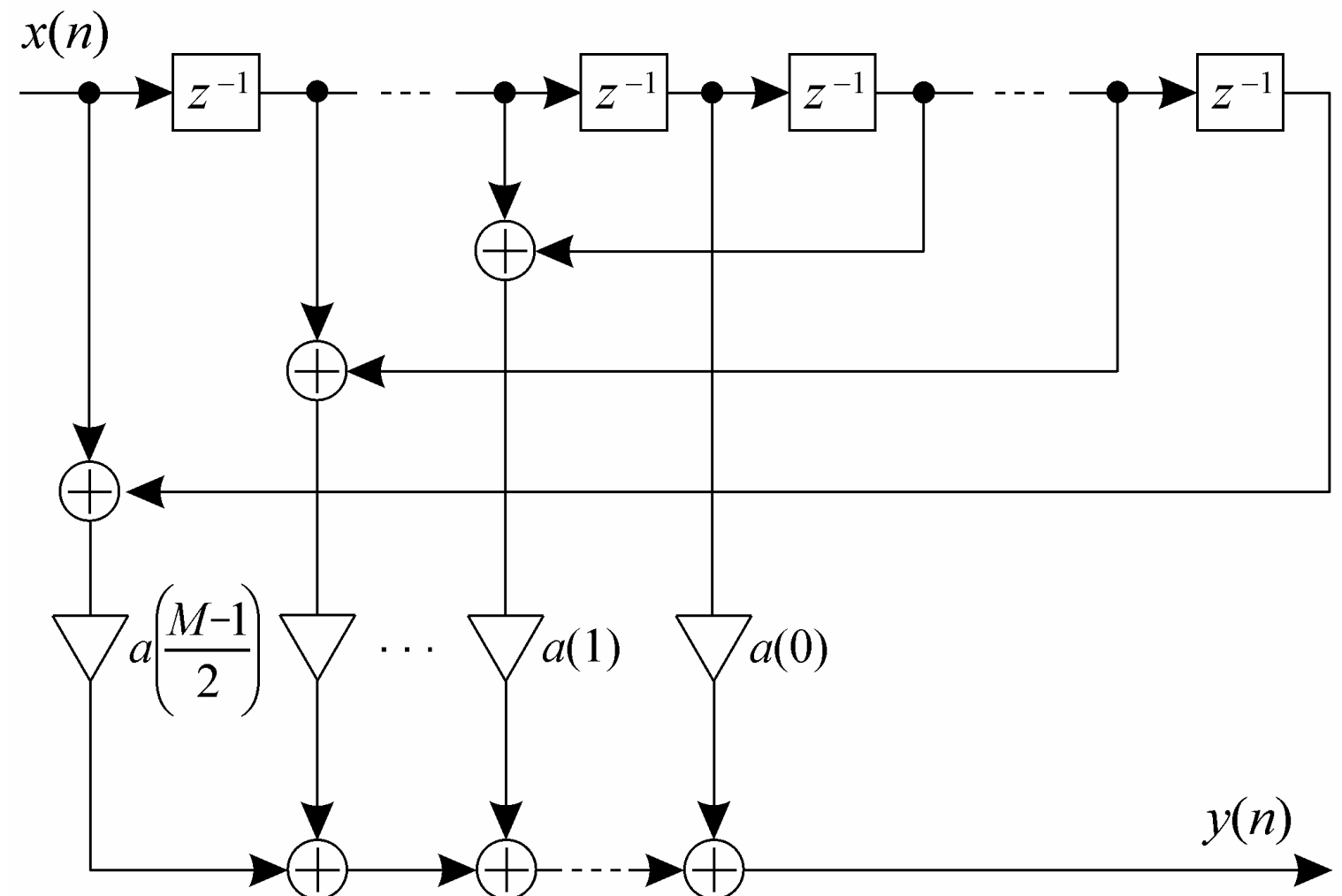
# Minimax Approximation with SPT Coefficients

- Each  $b(m,k) \neq 0$  represents **one adder** in hardware
- Number of terms per each coefficient is limited to a prescribed value  $P$

- Structure of compensator

- **Total number of adders**

$$A \leq \frac{(M+1)(P+1)}{2} - 1$$



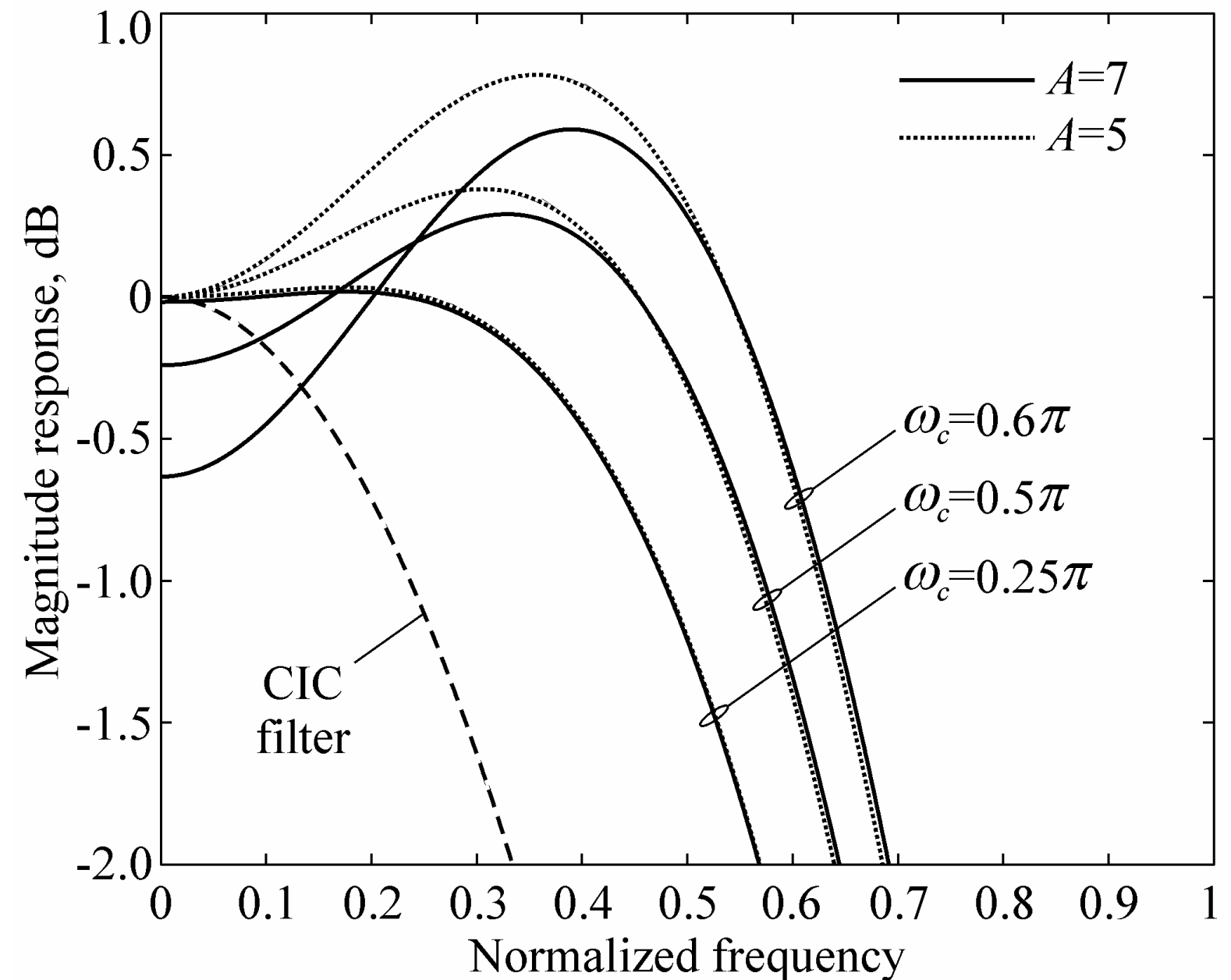
# Features of Proposed Compensators

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- Three examples are described
  - Compensators with three coefficients
  - Wideband compensators
  - Compensators with the lowest complexity

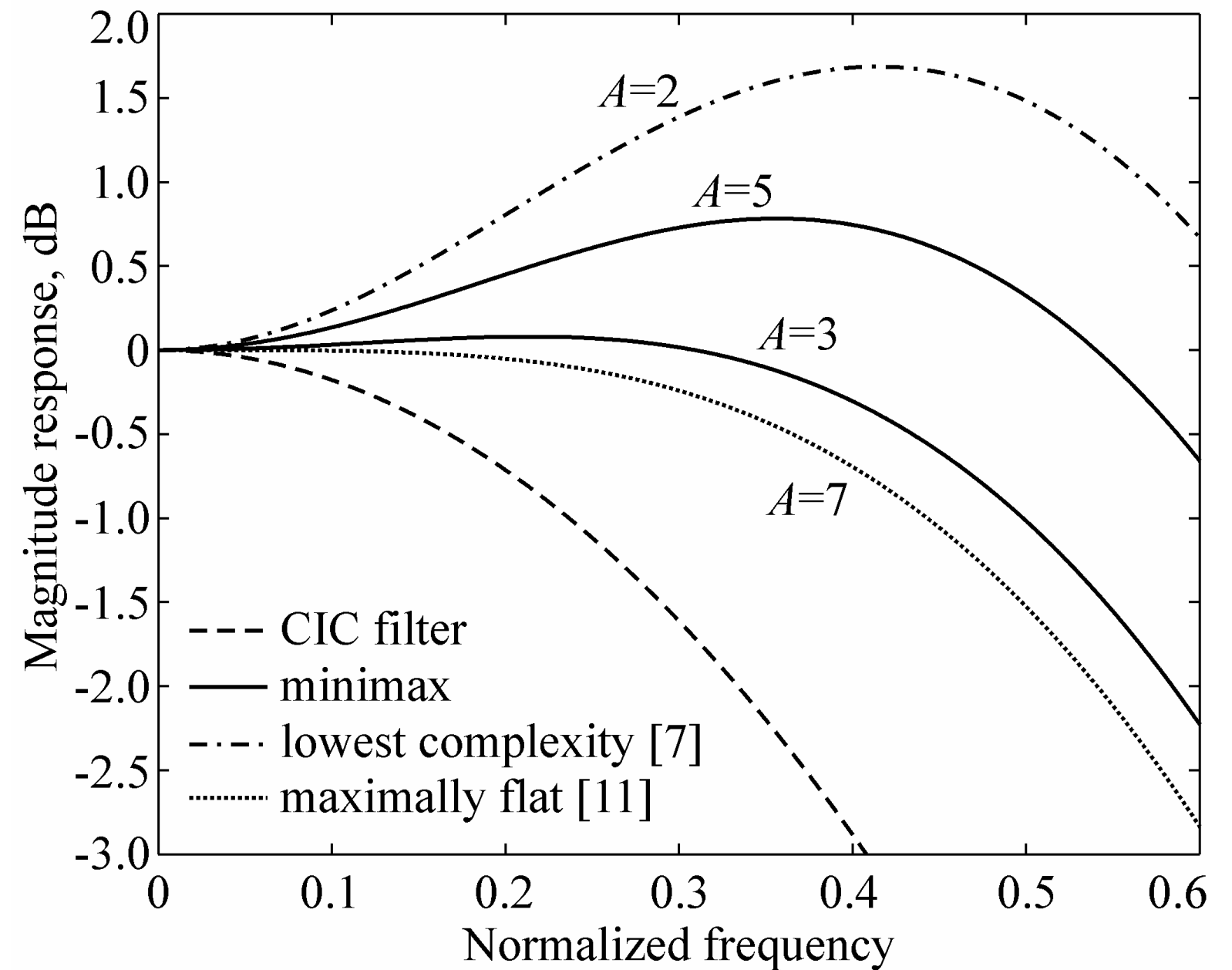
# Compensators With Three Coefficients

- $N=5, R=14$
- Narrowband
  - $\omega_c=0.25\pi$
- Wideband
  - $\omega_c=0.5\pi, 0.6\pi$
- Two compensators
  - $K=9$
  - $P=2$  results in  $A=5$
  - $P=3$  results in  $A=7$



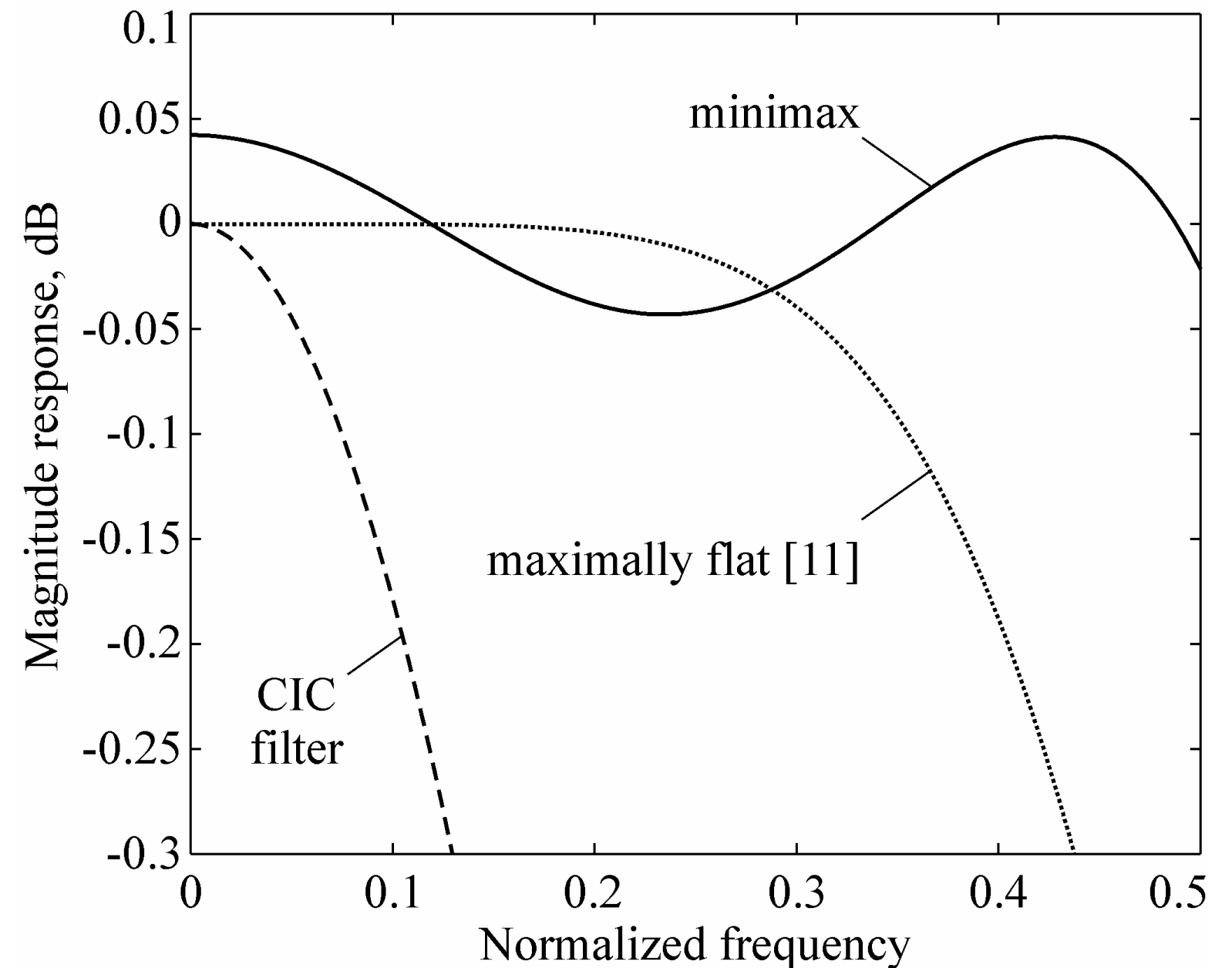
# Compensators With Three Coefficients

- Comparison with other compensators
- $N=5, R=14$
- $\omega_c=0.6\pi$



# Wideband Compensators

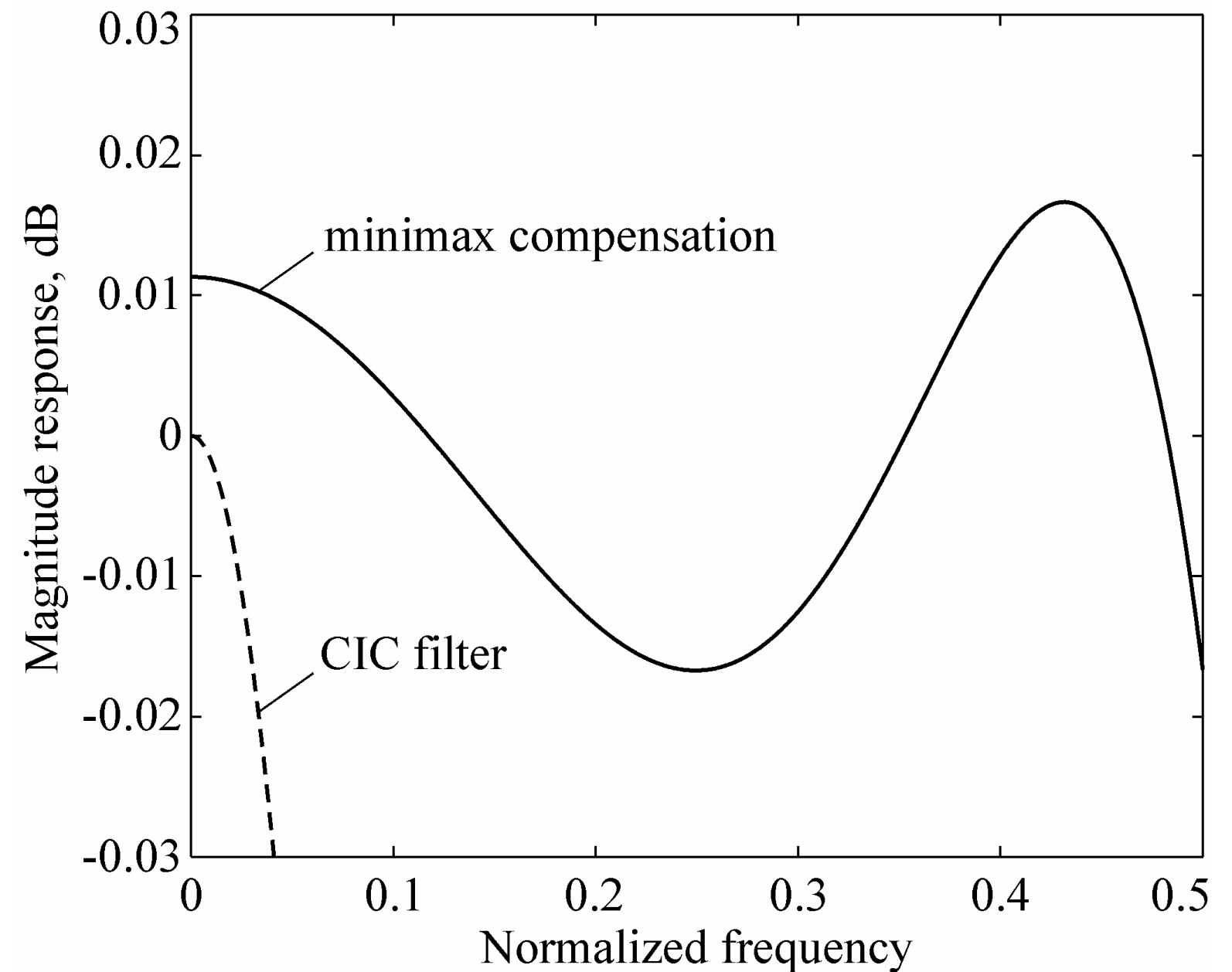
- $M=5$
- $N=5, R=32$
- $\omega_c=0.5\pi$
- MaxFlat compensator uses 15 adders
- Our compensator uses 14 adders





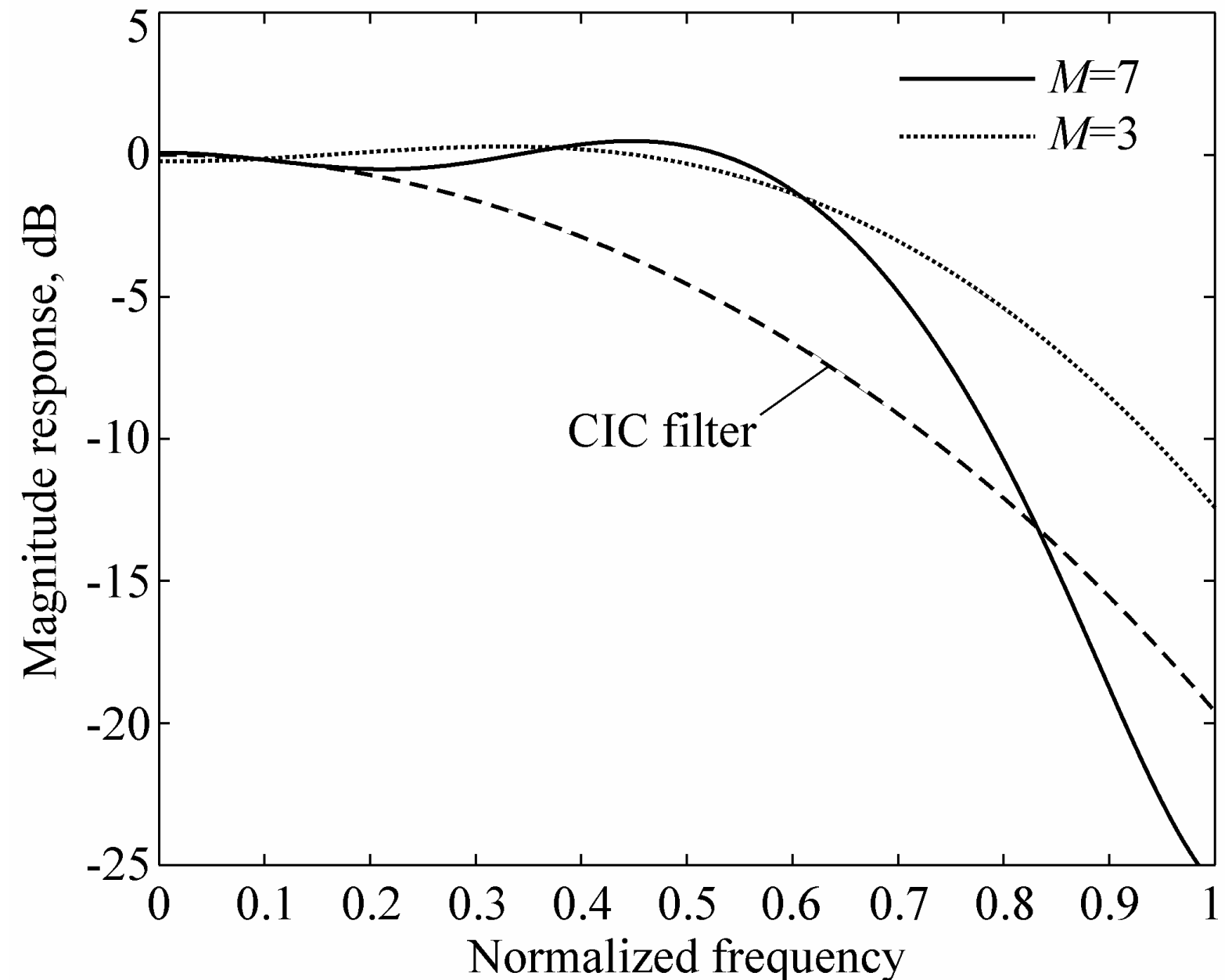
# Wideband Compensators

- $M=7$
- Our compensator uses 19 adders
- Compensation error less than 0.02dB



# Compensators With Lowest Complexity

- $P=1$
- $N=5, R=32, \omega_c=0.5\pi$
- Two compensators
  - $M=7$  with  $P=1$
  - $M=3$  with the same number of adders
- $M=7$  has a better rolloff characteristic



# Conclusion

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- The design of minimax CIC compensators over the **SPT coefficient space** has been presented
- The optimum compensators are obtained using the **global optimization** based on the interval analysis
  - It enables the design of the compensators with **high number of coefficients** and the **wideband** compensators
- Compared with the known SPT compensators, the proposed compensators generally result in a **better compensation** and a **lower complexity**