

Noise Robust Local Phase Coherence Based Method for Image Sharpness Assessment

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http://www.fer.unizg.hr/_download/repository/LPCcode.zip



1. Introduction

Image sharpness assessment is a very important issue in image acquisition and processing. Novel approaches in no-reference image sharpness assessment methods are based on **local phase coherence (LPC)**, rather than edge or frequency content analysis. It has been shown that the LPC based methods are closer to human observer assessments.

We propose *carefully designed complex wavelets* that provide a good tool for the local phase estimation. Moreover, we take a *special care of noise*. We apply thresholding in the wavelet domain and *merge several estimates* to achieve statistical robustness in the presence of noise. It results in the sharpness index that over-performs previously reported methods.

2. Robust Local Phase Coherence

Human observer assessment of sharpness is focused on **impulses** and **steps** of 1D signals, or on **points** and **edges** in images.

Complex wavelet analysis of sharp edges across a set of scales results in locally linear phase segments that intersect in a single point \rightarrow strong local linear phase coherence \rightarrow LPC can be used for sharpness assessment.

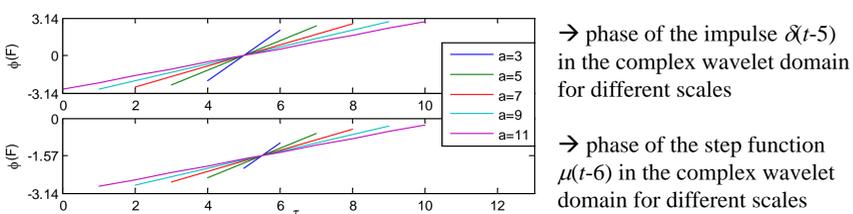
We use continuous complex mother wavelet

$$\psi(t) = \left[\mu\left(t + \frac{\pi}{\omega_0}\right) - \mu\left(t - \frac{\pi}{\omega_0}\right) \right] e^{j\omega_0 t}$$

that is sampled on unit circle to produce discrete wavelet function:

$$\psi_N(n) = [\mu(n + (N-1)/2) - \mu(n - (N-1)/2)] e^{j2\pi n/N}$$

where $N \in \{3, 5, 7, 9, 11\}$ and $n \in \mathbb{Z}$.



In 2D:

$$\psi_o(m, n) = \psi_k(m) \times \psi_l(n)$$

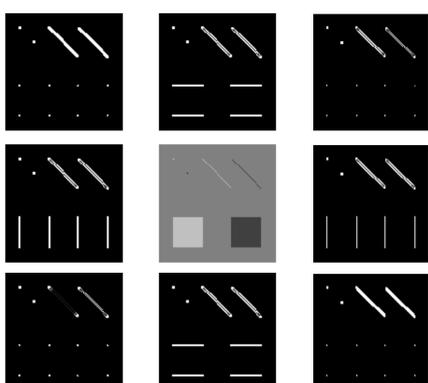
where $k, l \in \{-, 0, +\}$ correspond to 9 spatial orientations o .

We propose LPC strength measure:

$$S_{LPC}^{o,k} = (\pi - |\mathbf{w}^T \Phi|) / \pi$$

where Φ is a vector of the measured phases and \mathbf{w} are weights. The weights using 5 scales are: $\mathbf{w}_{\{5\}} = [1 \ -2.10 \ -0.44 \ 0.48 \ 1.06]^T$, using 4 scales are: $\mathbf{w}_{\{4\}} = [1 \ -2.06 \ -0.10 \ 1.16]^T$, and using 3 scales are: $\mathbf{w}_{\{3\}} = [1 \ -2.57 \ 1.57]^T$.

LPC strength measure is calculated for each orientation o and for each position k in the 1D signal or in the image \rightarrow results strongly depend on the orientation of edges in images \rightarrow

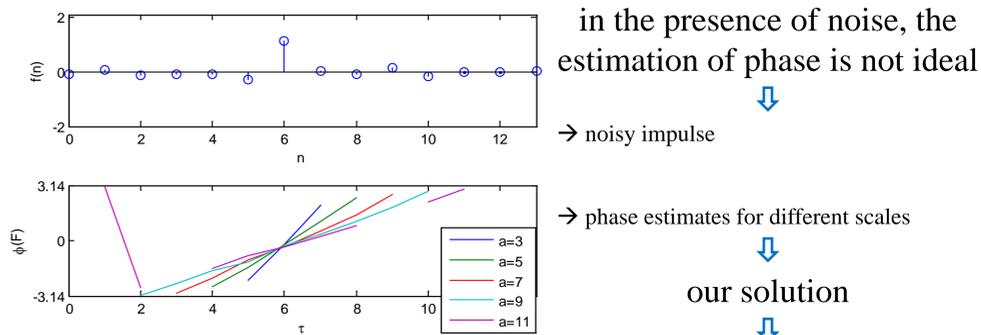


Spatial LPC map is a collection of all LPC strength maps:

$$S_{LPC}^{k} = \max(S_{LPC}^{o,k})$$



3. Phase Prediction in the Presence of Noise



Thresholding in the wavelet domain

if amplitude is smaller than a threshold \rightarrow phase estimate is non-accurate \rightarrow do not take it into the account

if phase estimates are available for all 5 scales \rightarrow calculate $S_{LPC,\{5\}}$ using weights $\mathbf{w}_{\{5\}}$
 if phase estimates are available for 4 scales \rightarrow calculate $S_{LPC,\{4\}}$ using weights $\mathbf{w}_{\{4\}}$
 if phase estimates are available only for 3 scales \rightarrow calculate $S_{LPC,\{3\}}$ using weights $\mathbf{w}_{\{3\}}$

Averaged LPC strength maps S_{LPC}

weighted moving average of the LPC strength maps with 5, 4 or 3 scales

4. Results

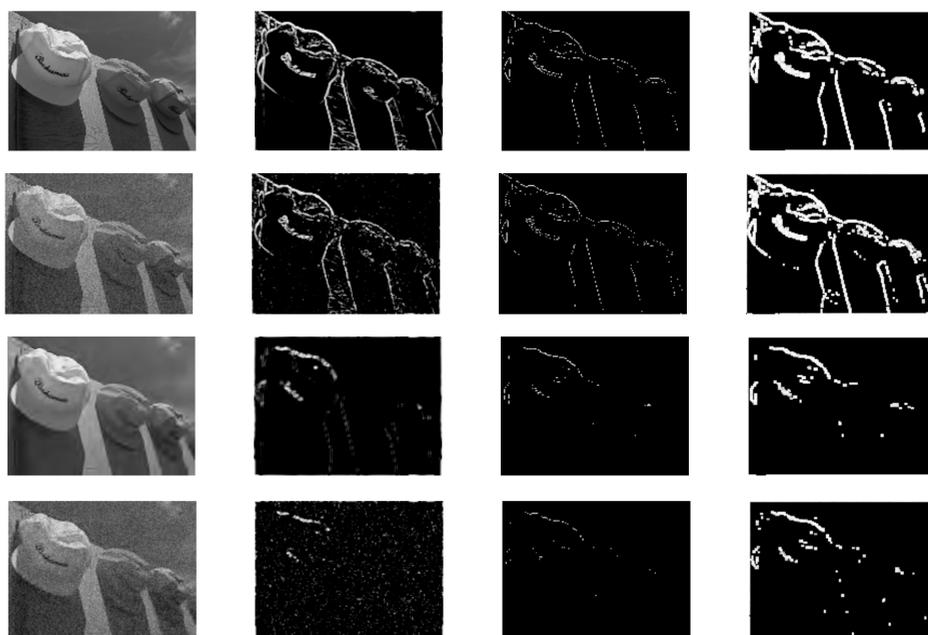
The method is applied on real world images \rightarrow rows top to bottom: hats, noisy hats, blurred hats, blurred and noisy hats.

LPC maps are found using three different methods \rightarrow columns left to right: noisy real-world image, LPC map using [1], LPC map using $S_{LPC,\{5\}}$ only, LPC map using averaged S_{LPC} .

[1] R. Hassen, Z. Wang, and M. Salama, "Image sharpness assessment based on local phase coherence," *IEEE Transactions on Image Processing*, vol. 22, no. 7, pp. 2798 – 2810, 2013.

	S_{LPC} form [1]	$S_{LPC,\{5\}}$	S_{LPC}
hats	0.923	0.243	0.871
noisy hats	0.914	0.255	0.917
blurred hats	0.904	0.091	0.451
blurred noisy hats	0.879	0.056	0.431

Sharpness index [1] for image sharpness assessment:
 \rightarrow 1 for totally sharp and
 \rightarrow 0 for totally blurred images.



Benefits of the proposed wavelets: the resulting LPC maps are sharp, precisely reflecting the image edges and fine details \rightarrow noise robust LPC estimate can be used as an edge detector, too.